

Proving a Concurrent Program Correct by Demonstrating It Does Nothing

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<https://github.com/boogie-org/boogie>



<https://www.rise4fun.com/civl>

Credits



Cormac Flanagan



Stephen N. Freund



Serdar Tasiran

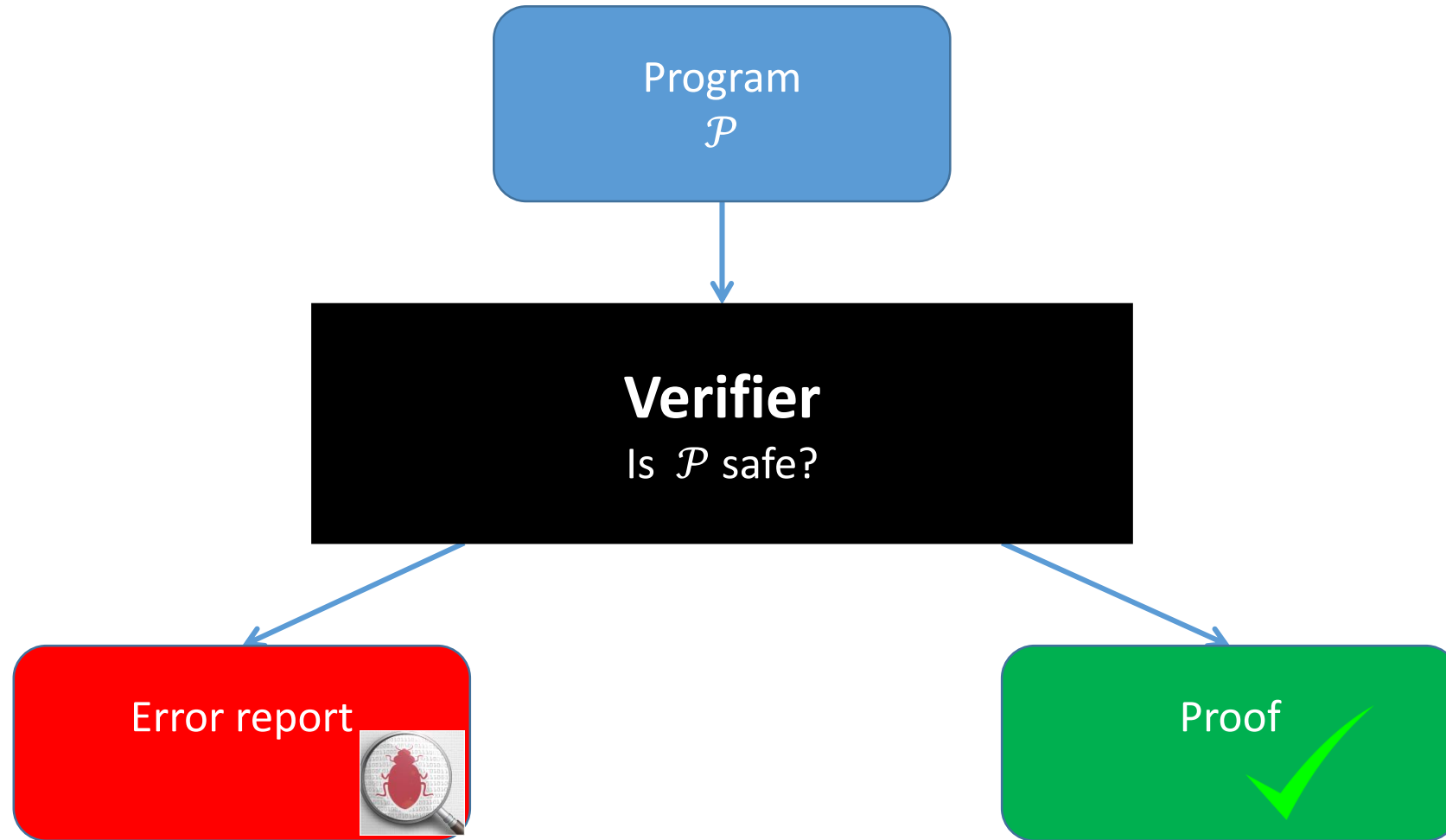


Tayfun Elmas

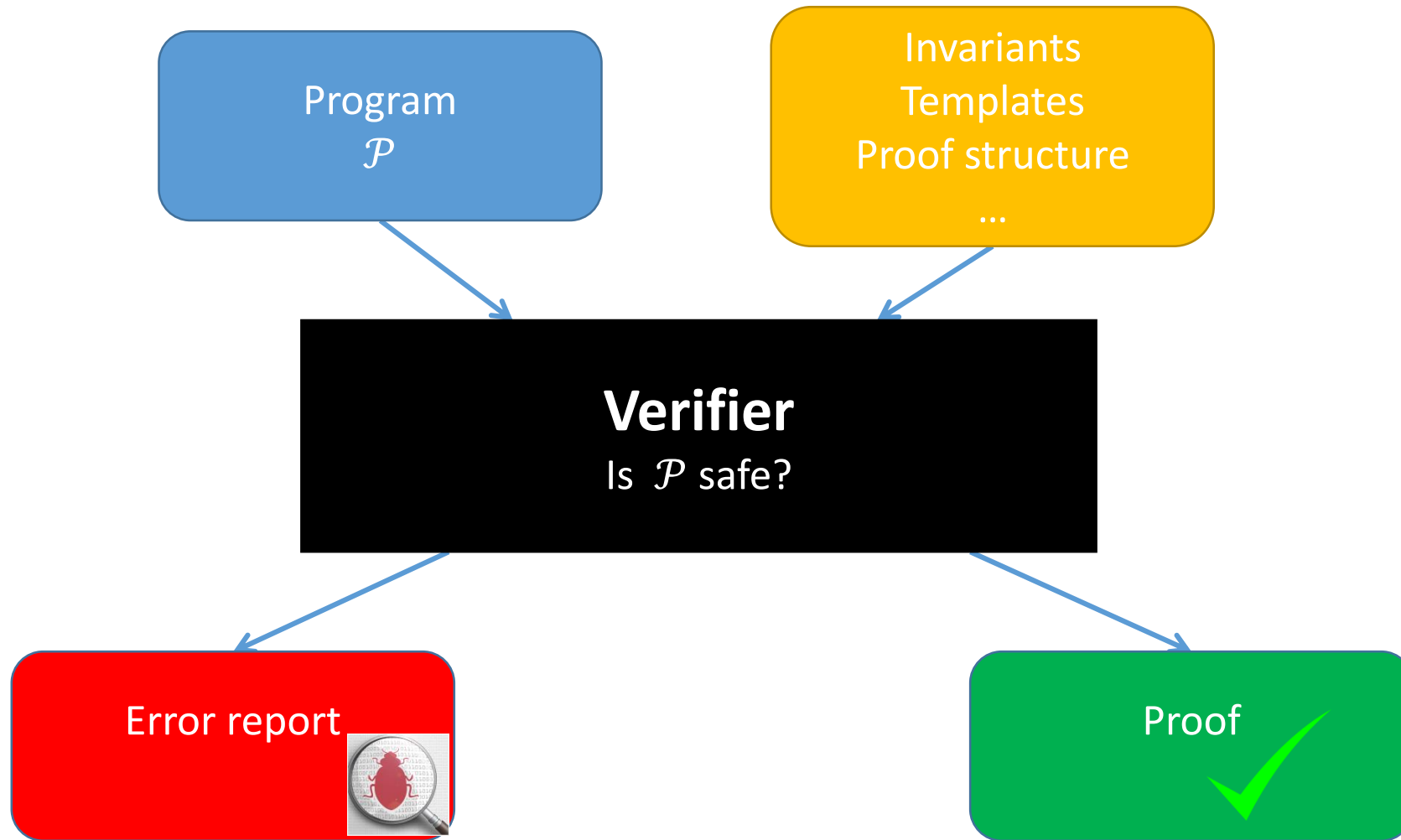


Chris Hawblitzel

Program verification



Program verification



Reasoning about transition systems

- Transition system $(Var, Init, Next, Safe)$

Var (Variables)

$Init$ (Initial state predicate over Var)

$Next$ (Transition predicate over $Var \cup Var'$)

$Safe$ (Safety predicate over Var)

- Inductive invariant Inv

$Init \Rightarrow Inv$ (Initialization)

$Inv \wedge Next \Rightarrow Inv'$ (Preservation)

$Inv \Rightarrow Safe$ (Safety)

Structured program vs. Transition relation

```

      a: x := 0
b: acquire(l)   || acquire(l)
c: t1 := x      || t2 := x
d: t1 := t1+1   || t2 := t2+1
e: x := t1      || x := t2
f: release(l)   || release(l)
      g: assert x = 2
  
```

Procedures and dynamic thread creation
complicate transition relation further!

Init: $pc = pc_1 = pc_2 = a$

Next:

$$\begin{aligned}
 pc &= a \wedge pc' = pc'_1 = pc'_2 = b \wedge x' = 0 \wedge eq(l, t_1, t_2) \\
 pc_1 &= b \wedge pc'_1 = c \wedge \neg l \wedge l' \wedge eq(pc, pc_2, x, t_1, t_2) \\
 pc_1 &= c \wedge pc'_1 = d \wedge t'_1 = x \wedge eq(pc, pc_2, l, x, t_2) \\
 pc_1 &= d \wedge pc'_1 = e \wedge t'_1 = t_1 + 1 \wedge eq(pc, pc_2, l, x, t_2) \\
 pc_1 &= e \wedge pc'_1 = f \wedge x' = t_1 \wedge eq(pc, pc_2, l, t_1, t_2) \\
 pc_1 &= f \wedge pc'_1 = g \wedge \neg l' \wedge eq(pc, pc_2, x, t_1, t_2) \\
 pc_2 &= b \wedge pc'_2 = c \wedge \neg l \wedge l' \wedge eq(pc, pc_1, x, t_1, t_2) \\
 pc_2 &= c \wedge pc'_2 = d \wedge t'_2 = x \wedge eq(pc, pc_1, l, x, t_1) \\
 pc_2 &= d \wedge pc'_2 = e \wedge t'_2 = t_2 + 1 \wedge eq(pc, pc_1, l, x, t_1) \\
 pc_2 &= e \wedge pc'_2 = f \wedge x' = t_2 \wedge eq(pc, pc_1, l, t_1, t_2) \\
 pc_2 &= f \wedge pc'_2 = g \wedge \neg l' \wedge eq(pc, pc_1, x, t_1, t_2) \\
 pc_1 &= pc_2 = g \wedge pc' = g \wedge eq(pc_1, pc_2, l, x, t_1, t_2)
 \end{aligned}$$

Safe: $pc = g \Rightarrow x = 2$

Interference freedom and Owicki-Gries

$$\frac{\Psi_1: \{P_1\} C_1 \{Q_1\} \quad \Psi_2: \{P_2\} C_2 \{Q_2\} \quad \Psi_1, \Psi_2 \text{ interference free}}{\{P_1 \wedge P_2\} C_1 \parallel C_2 \{Q_1 \wedge Q_2\}}$$

- Example: $\{x = 0\} x := x + 1 \parallel x := x + 2 \{x = 3\}$

$$\begin{array}{c} \{x = 0\} \\ \{x = 0\} \\ P_1: \{x = 0 \vee x = 2\} \\ \quad x := x + 1 \\ Q_1: \{x = 1 \vee x = 3\} \\ \{Q_1 \wedge Q_2\} \\ \{x = 3\} \end{array} \parallel \begin{array}{c} \{x = 0\} \\ P_2: \{x = 0 \vee x = 1\} \\ \quad x := x + 2 \\ Q_2: \{x = 2 \vee x = 3\} \end{array}$$

Interference freedom:

$$\begin{array}{ll} \{P_1 \wedge P_2\} x := x + 2 \{P_1\} & \{P_2 \wedge P_1\} x := x + 1 \{P_2\} \\ \{Q_1 \wedge P_2\} x := x + 2 \{Q_1\} & \{Q_2 \wedge P_1\} x := x + 1 \{Q_2\} \end{array}$$

Ghost variables

Need to refer to other thread's state

- local variables
- program counter

- Example: $\{x = 0\} x := x + 1 \parallel x := x + 1 \{x = 2\}$

$$\begin{array}{c} \{x = 0\} \\ [done_1 := false; done_2 := false] \\ P_1: \{ \neg done_1 \wedge (\neg done_2 \Rightarrow x = 0) \wedge (done_2 \Rightarrow x = 1) \} \\ [x := x + 1; done_1 := true] \\ Q_1: \{ done_1 \wedge (\neg done_2 \Rightarrow x = 1) \wedge (done_2 \Rightarrow x = 2) \} \\ \{x = 2\} \end{array} \parallel \begin{array}{c} P_2: \{ \neg done_2 \wedge (\neg done_1 \Rightarrow x = 0) \wedge (done_1 \Rightarrow x = 1) \} \\ [x := x + 1; done_2 := true] \\ Q_2: \{ done_2 \wedge (\neg done_1 \Rightarrow x = 1) \wedge (done_1 \Rightarrow x = 2) \} \end{array}$$

Rely/Guarantee

Rely/Guarantee specifications $C \models (P, R, G, Q)$ for individual threads
and composition rule
allow for modular proofs of loosely-coupled systems.

$$\begin{array}{c} \{x \geq 0\} \\ x := x + 1 \parallel x := x + 1 \quad P = Q = (x \geq 0) \quad R = G = (x' \geq x) \\ \{x \geq 0\} \end{array}$$

Multi-layered refinement proofs

$$\frac{P_1 \preceq P_2 \preceq \dots \preceq P_{n-1} \preceq P_n \quad P_n \text{ is safe}}{P_1 \text{ is safe}}$$

[skip]
||

Advantages of structured proofs:

Better for humans: easier to construct and maintain

Better for computers: localized/small checks → easier to automate

Programs that do nothing cannot go wrong

Refinement is well-studied

- Logic

- $P(x, x') \Rightarrow Q(x, x')$

- Labeled transition systems

- Language containment
 - Simulation (forward, backward, upward, downward, diagonal, sideways, ...)
 - Bisimulation (vanilla, mint, lavender, barbed, triangulated, complicated, ...)
 - ...

Refinement is difficult for programs

- Programs are complicated
 - Complex control and data
- Gap between program syntax and abstractions
- ... especially for concurrent programs
- ... especially for interactive proof construction

CIVL: Construct correct concurrent programs layer by layer

- Operates on program syntax
- Organizes proof as a sequence of program layers with increasingly coarse-grained atomic actions
- All layers and supporting invariants expressed together in one textual unit
- Automatically-generated verification conditions

```
procedure P(...) { S }  
S1; S2  
  
if (e) S1 else S2  
  
while (e) S  
  
call P  
  
async call P  
  
call P1 || P2  
  
call A
```

Gated atomic actions [Elmas, Q, Tasiran 2009]

(**Gate**, **Transition**)
single-state predicate two-state predicate

Command	Gate	Transition
$x := x+y$	<i>true</i>	$x' = x + y \wedge y' = y$
havoc x	<i>true</i>	$y' = y$
assert $x < y$	$x < y$	$x' = x \wedge y' = y$
assume $x < y$	<i>true</i>	$x < y \wedge x' = x \wedge y' = y$

Lock specification

var lock : ThreadID U {nil}

Acquire(): [assume lock == nil; lock := tid]

Release(): [assert lock == tid; lock := nil]

- Unifies precondition and postcondition
- Primitive for modeling a (concrete or abstract) concurrent program

Operational semantics

- Program configuration $(g, \{(\ell, s) \cdot \vec{f}\} \uplus \mathcal{T})$
- Transition relation \Rightarrow between configurations (and failure configuration \perp)
- Safety: $\neg \exists g \ell: (g, (\ell, Main)) \Rightarrow^* \perp$
- $Good(P) = \{g \mid \neg \exists \ell: (g, (\ell, Main)) \Rightarrow^* \perp\}$
- $Trans(P) = \{(g, g') \mid \exists \ell: (g, (\ell, Main)) \Rightarrow^* (g', \emptyset)\}$
- $P_1 \preceq P_2$: (1) $Good(P_2) \subseteq Good(P_1)$ (2) $Good(P_2) \circ Trans(P_1) \subseteq Trans(P_2)$
 P_2 preserves failures P_2 preserves final states


```
const c >= 0;
var x;

call Main();
Main() {
    // Create c threads
    // each executing Incr
}
Incr() {
    acquire();
    assert x ≥ 0;
    x := x + 1;
    release();
}
```



[assert $x \geq 0$]

```
const c >= 0;
var x;

call Main();
Main() {
    x := 0;
    // Create c threads
    // each executing Incr
}
Incr() {
    acquire();
    assert x ≥ 0;
    x := x + 1;
    release();
}
```



[]

Programs constructed with CIVL

- Concurrent garbage collector [Hawblitzel, Petrank, Q, Tasiran 2015]
- FastTrack2 race-detection algorithm [Flanagan, Freund, Wilcox 2018]
- Lock-protected memory atop TSO [Hawblitzel]
- Thread-local heap atop shared heap [Hawblitzel, Q]
- Two-phase commit [K, Q, Henzinger 2018]
- Work-stealing queue, Treiber stack, Ticket, ...

Program layers in CIVL

- A CIVL program denotes a sequence of concurrent programs (layers)
 - chained together by a refinement-preserving transformation
- Transformation between program layers combines
 - Atomization: Transform **statement S** into **atomic block [S]**
 - Summarization: Transform **atomic block [S]** into **atomic action A**
 - Abstraction: Replace **atomic action A** with **atomic action B**

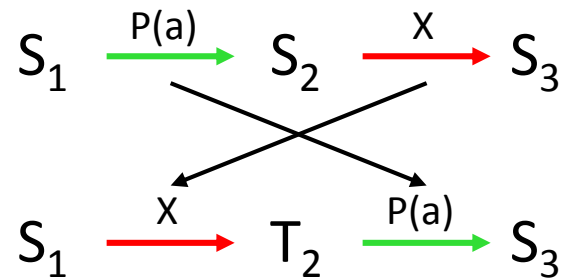
Right and left movers [Lipton 1975]

Integer a “Semaphore”

“wait”

$P(a) = [\text{assume } a > 0; a := a - 1]$

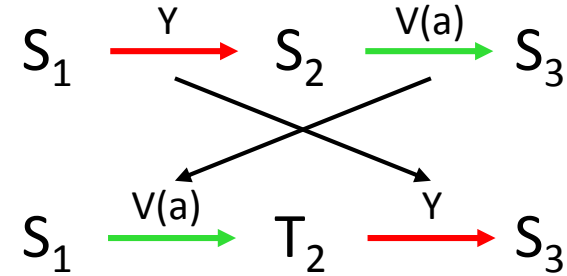
right mover (R)



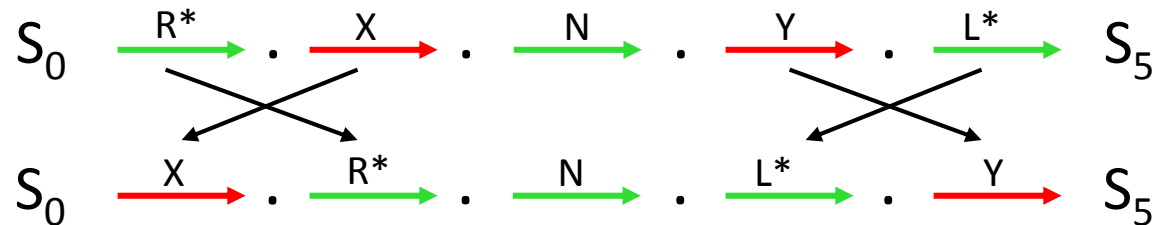
“signal”

$V(a) = [a := a + 1]$

left mover (L)



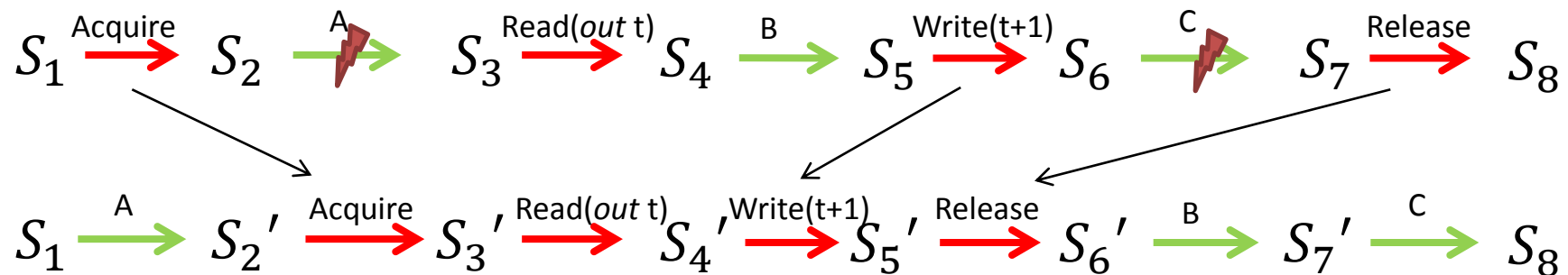
Sequence $R^*; (N+\epsilon); L^*$ is atomic



Atomic actions can fail

```

var x : int, lock : ThreadID U {nil}
Acquire():  [assume lock == nil; lock := tid]
Release():  [assert lock == tid; lock := nil]
Read(out r): [assert lock == tid; r := x]
Write(v):   [assert lock == tid; x := v]
    
```



Commutativity: $R X \rightarrow X R$ $X L \rightarrow L X$

Forward preservation: $R X \perp \rightarrow X \perp$ $X L \perp \rightarrow X \perp$

Backward preservation: $X \perp \rightarrow L X \perp$

Nonblocking and Cooperation

$[x := 0]$ \parallel $[x := x + 1]^N$
 $[\text{assert } x = 0]$ \parallel $[\text{assume false}]^L$



$[x := 0]$ \parallel $[x := x + 1;$
 $[\text{assert } x = 0]$ \parallel $\text{assume false}]$

Left movers must be **nonblocking**

$[x := 0]$ \parallel $[x := x + 1]^N$
 $[\text{assert } x = 0]$ \parallel $\text{while (true) [skip]}^L$



$[x := 0]$ \parallel $[x := x + 1;$
 $[\text{assert } x = 0]$ \parallel $\text{while (true) skip}]$

Termination? Too strong.

$[x := 0]$ \parallel $[x := x + 1]^N$
 $[\text{assert } x = 0]$ \parallel $\text{while (*) [skip]}^L$

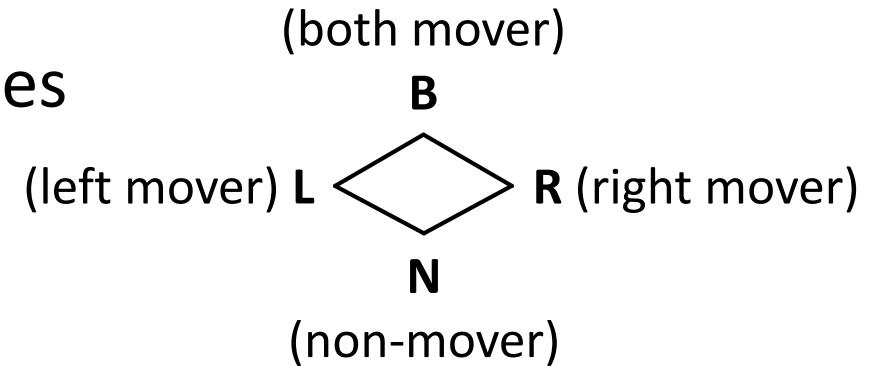


$[x := 0]$ \parallel $[x := x + 1;$
 $[\text{assert } x = 0]$ \parallel $\text{while (*) skip}]$

Cooperation: always possible to terminate

Mover types in CIVL

1. Atomic actions are annotated with mover types



2. Induced logical commutativity conditions

Commutativity (G_1, T_1) is R or (G_2, T_2) is L
 $\forall S_1 S_2 S_3 \exists S'_2: G_1(S_1) \wedge G_2(S_1) \wedge T_1(S_1, S_2) \wedge T_2(S_2, S_3) \Rightarrow T_2(S_1, S'_2) \wedge T_1(S'_2, S_3)$

Nonblocking (G, T) is L
 $\forall S \exists S': G(S) \Rightarrow T(S, S')$

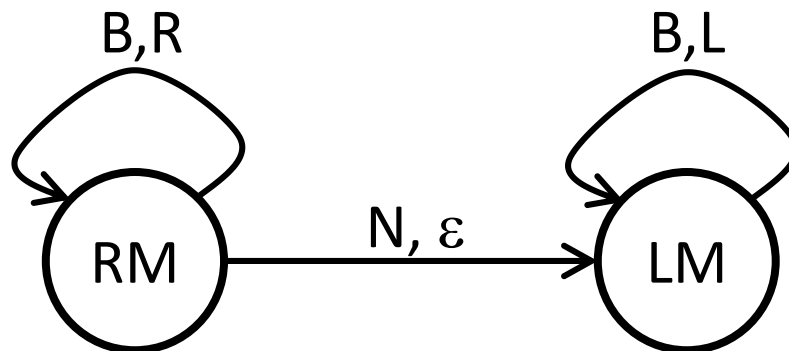
Forward preservation (G_1, T_1) is R or (G_2, T_2) is L
 $\forall S S': G_1(S) \wedge G_2(S) \wedge T_1(S, S') \Rightarrow G_2(S')$

Backward preservation (G_2, T_2) is L
 $\forall S S': G_2(S) \wedge T_2(S, S') \wedge G_1(S') \Rightarrow G_1(S)$

3. Atomization of composite statements

Atomization ($S \rightarrow [S]$)

- We justified rearranging executions to create “atomic transactions”
- Goal: statically create atomic blocks with only rearrangeable executions
- Each path in S behaves like the automaton
 - Type system [Flanagan, Q 2003]
 - Simulation relation on labeled graphs [Hawblitzel, Petrank, Q, Tasiran 2015]



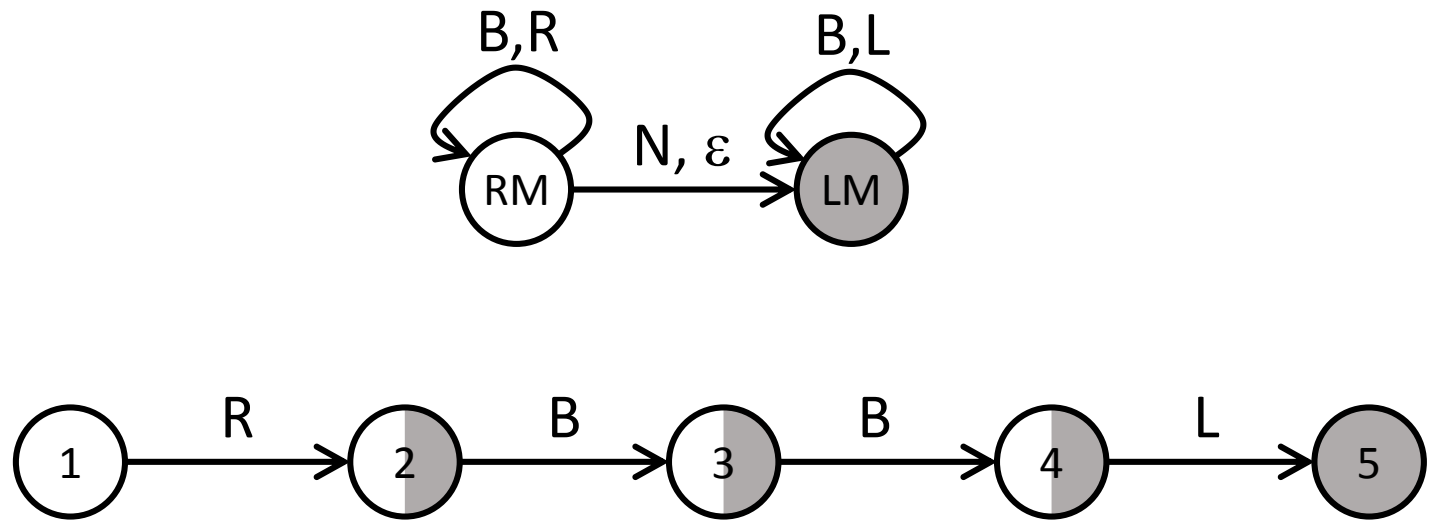
Example: Atomizing nonatomic increment

```

var x : int, lock : ThreadID U {nil}
Acquire():  [assume lock == nil; lock := tid]      R
Release():  [assert lock == tid; lock := nil]      L
Read(out r): [assert lock == tid; r := x]          B
Write(v):   [assert lock == tid; x := v]           B
    
```

```

proc Inc ()
  var t
  1 Acquire()
  2 Read(out t)
  3 Write(t + 1)
  4 Release()
  5
    
```



Simulation computation [Henzinger, Henzinger, Kopke 1995]

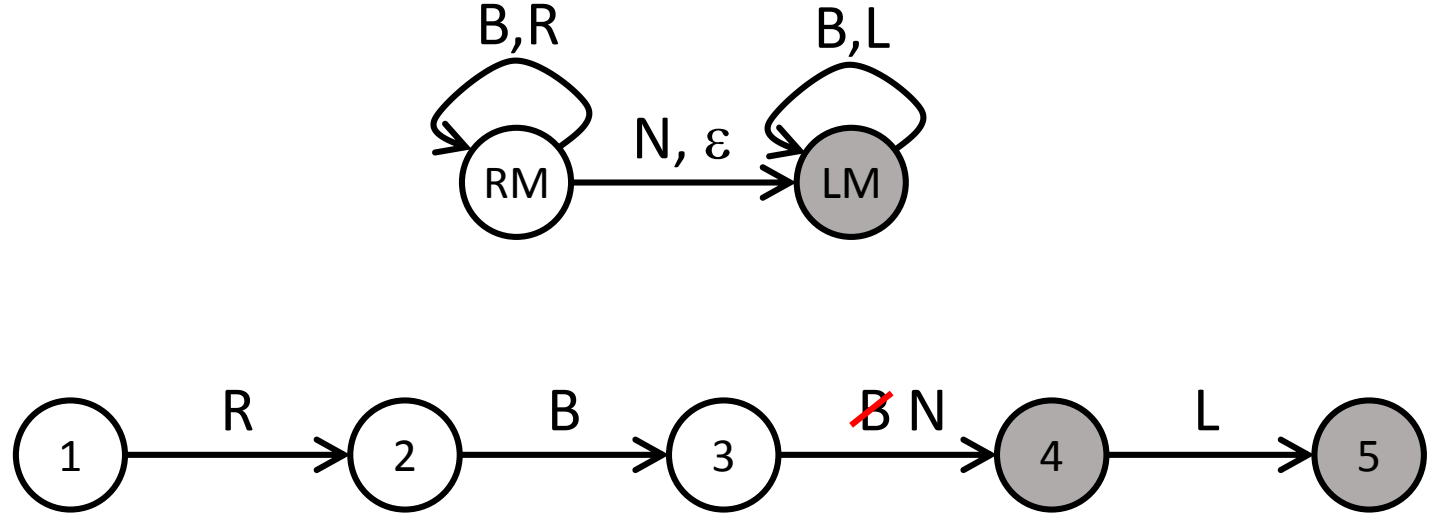
Example: Atomizing nonatomic increment

```

var x : int, lock : ThreadID U {nil}
Acquire():  [assume lock == nil; lock := tid]      R
Release():  [assert lock == tid; lock := nil]      L
Read(out r): [assert lock == tid; r := x]          B
Write(v):   [assert lock == tid; x := v]          B N
Read2(out t): [t := x]                            N
    
```

```

proc Inc ()
  var t
  1 Acquire()
  2 Read(out t)
  3 Write(t + 1)
  4 Release()
  5
    
```

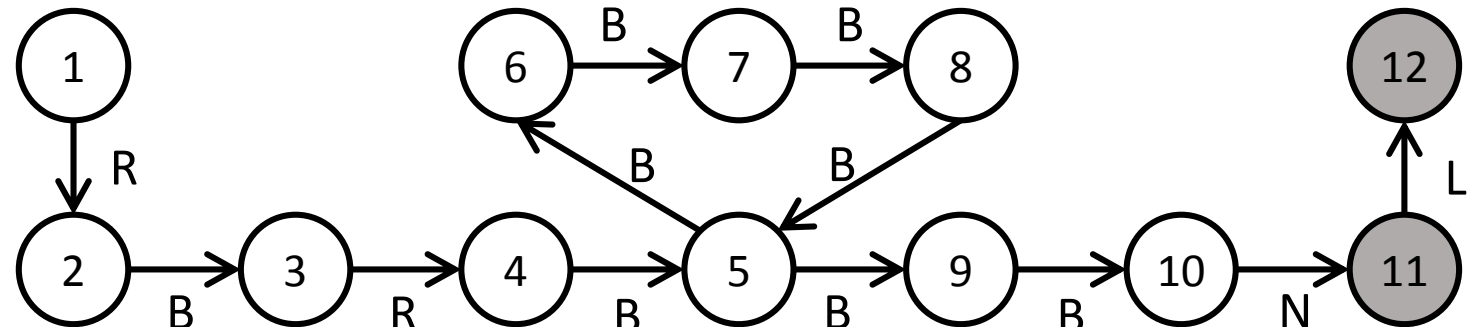


Simulation computation [Henzinger, Henzinger, Kopke 1995]

Example: Resizing an array

```
proc DoubleSize ()
  var t, B, v
1  Acquire()
2  GetLen(out t)
3  B := Allocate(2*t)
4  i := 0
5  while (i < t)
6    Read(i, out v)
7    B[i] := v
8    i := i + 1
9  Switch(B)
10 SetLen(2*t)
11 Release()
12
```

```
var A : Array, len : Nat, lock : ThreadID U {nil}
Acquire():    [assume lock == nil; lock := tid]    R
Release():    [assert lock == tid; lock := nil]    L
GetLen(out r): [assert lock == tid; r := len]      B
GetLen2(out r): [r := len]                        N
SetLen (v):    [assert lock == tid; len := v]      N
Read(i, out r): [assert lock == tid; r := A[i]]    B
Switch(B):    [assert lock == tid; A := B]         B
```



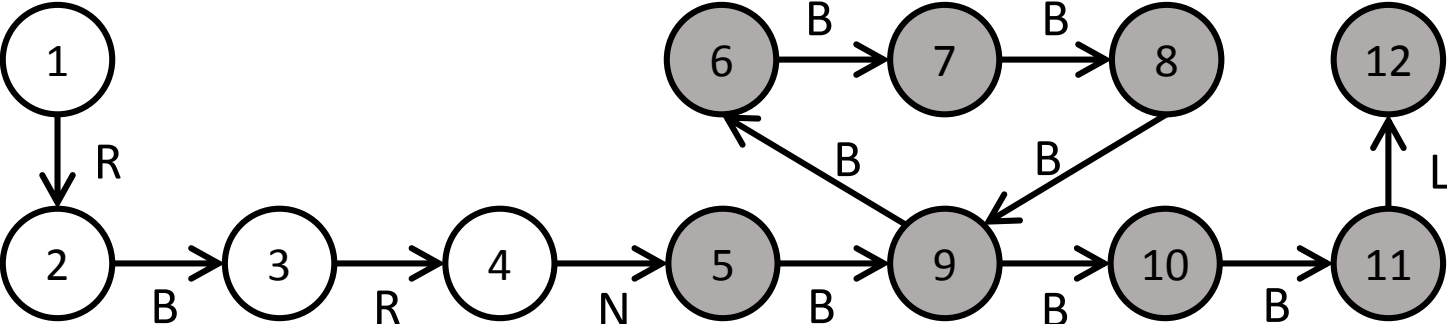
Example: Resizing an array

```

proc DoubleSize ()
  var t, B, v
  1 Acquire()
  2 GetLen(out t)
  3 B := Allocate(2*t)
  4 SetLen(2*t)
  5 i := 0
  6 while (i < t)
  7   Read(i, out v)
  8   B[i] := v
  9   i := i + 1
  10 Switch(B)
  11 Release()
  12
  
```

```

var A : Array, len : Nat, lock : ThreadID U {nil}
Acquire():      [assume lock == nil; lock := tid]      R
Release():      [assert lock == tid; lock := nil]      L
GetLen(out r):  [assert lock == tid; r := len]         B
GetLen2(out r): [r := len]                             N
SetLen (v):     [assert lock == tid; len := v]         N
Read(i, out r): [assert lock == tid; r := A[i]]        B
Switch(B):      [assert lock == tid; A := B]           B
  
```



Summarization ($[S] \rightarrow A$)

Within an atomic block, sequential reasoning suffices to obtain an atomic action.

```
Acquire: [assume lock == nil; lock := tid;  
Read:   assert lock == tid; t := x;  
Write:  assert lock == tid; x := t + 1;  
Release: assert lock == tid; lock := nil ]
```



```
Inc: [assume lock == nil; x := x + 1]
```

Abstraction ($A \rightarrow B$)

(G_1, A_1) refines (G_2, A_2)

iff

$$G_2 \Rightarrow G_1$$

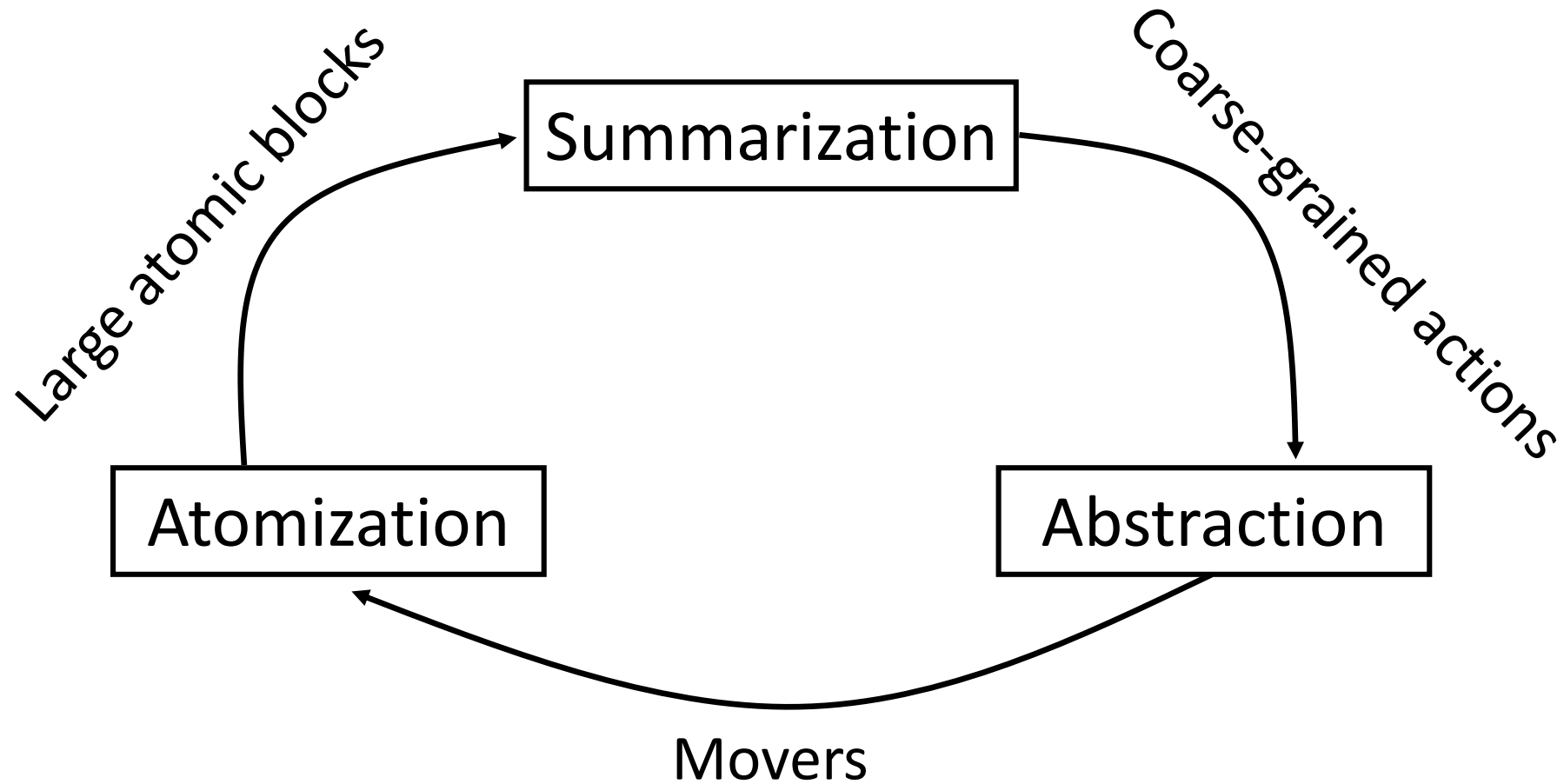
$$G_2 \bullet A_1 \Rightarrow A_2$$

$[g := g + 1]$ refines $[\text{assert } 0 \leq g; g := g + 1]$

$[g := g + 1]$ refines $[\text{var } g_ = g; \text{havoc } g; \text{assume } g_ \leq g]$

$[g := h]$ refines $/* 0 \leq h */ [\text{havoc } g; \text{assume } 0 \leq g]$

Atomization, summarization, and abstraction are symbiotic [Elmas, Q, Tasiran 2009]



Abstraction enables stronger mover types

Read and Write are conflicting (non-movers)

action Read(*out* r):
r := x

action Write (v):
x := v



action Read(*out* r):
assert lock == tid
r := x

action Write (v):
assert lock == tid
x := v

Strengthening the gates satisfies commutativity

Inc is blocking

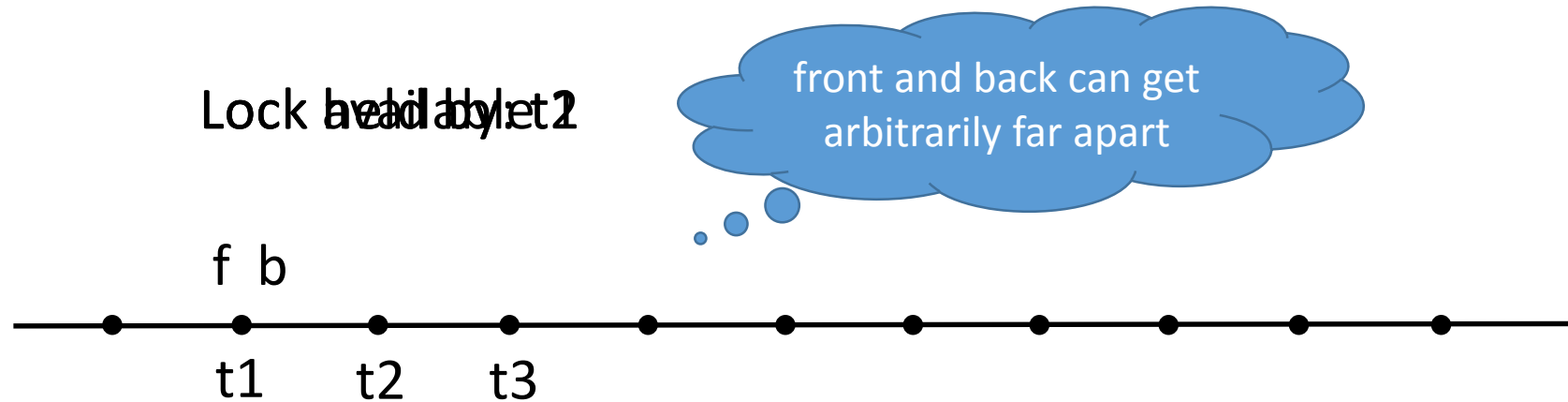
action Inc():
assume lock == nil
x := x + 1



action Inc():
x := x + 1

Weakening the transition
makes Inc nonblocking

Example: Ticket lock



```
var back  
var front
```

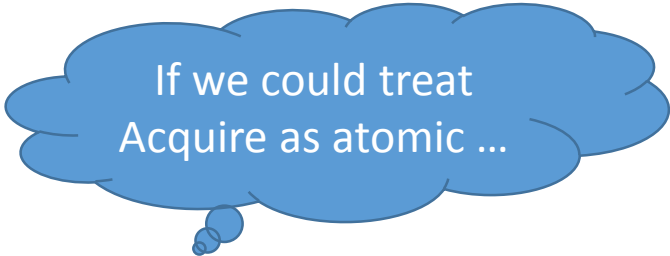
```
Acquire() {  
    var ticket  
    [ ticket := back; back := back + 1 ]  
    [ assume ticket == front ]  
}
```

```
Release() {  
    [ front := front + 1 ]  
}
```

Example: Ticket lock

```
var back  
var front
```

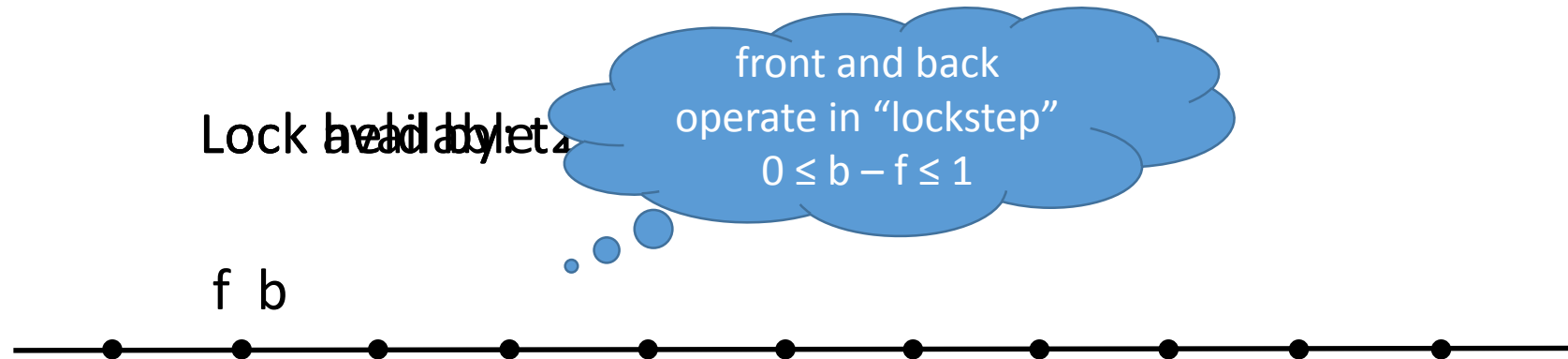
```
Acquire() {  
  var ticket  
  [ ticket := back; back := back + 1;  
    assume ticket == front ]  
}
```



If we could treat
Acquire as atomic ...

```
Release() {  
  [ front := front + 1 ]  
}
```

Example: Ticket lock



```
var back  
var front
```

```
Acquire() {  
    var ticket  
    [ assume front == back;  
      back := back + 1 ]  
}
```

```
Release() {  
    [ front := front + 1 ]  
}
```

```

var T
var front
Invariant: T = (-∞, back) }

Acquire() {
  var ticket
  [ havoc ticket; assume !T[ticket]; T[ticket] := true ] R
  [ assume ticket == front ] N
}

Release() {
  [ front := front + 1 ]
}

```

```

var back
var front

Acquire() {
  var ticket
  [ ticket := back; back := back + 1 ] N
  [ assume ticket == front ] N
}

Release() {
  [ front := front + 1 ]
}

```

```
var T
var front
```

```
Acquire() {
  var ticket
  [ havoc ticket; assume !T[ticket]; T[ticket] := true;
  assume ticket == front ]
}
```

```
Release() {
  [ front := front + 1 ]
}
```

```
var T
var front
```

```
Acquire() {
  var ticket
  [ havoc ticket; assume !T[ticket]; T[ticket] := true ] R
  [ assume ticket == front ] N
}
```

```
Release() {
  [ front := front + 1 ]
}
```

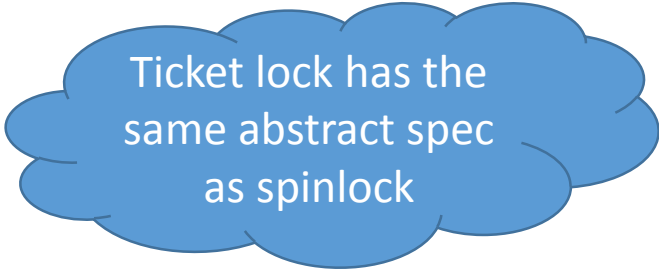
```
var back
var front
```

```
Acquire() {
  var ticket
  [ ticket := back; back := back + 1 ] N
  [ assume ticket == front ] N
}
```

```
Release() {
  [ front := front + 1 ]
}
```

var lock

```
Acquire() {  
  [ assume lock == nil;  
    lock := tid ]  
}
```



Ticket lock has the
same abstract spec
as spinlock

```
Release() {  
  [ assert lock == tid;  
    lock := nil ]  
}
```

Invariant: if lock == nil then $T = (-\infty, \text{front})$ else $T = (-\infty, \text{front}]$

var T
var front

```
Acquire() {  
  [ assume !T[front]; T[front] := true ]  
}
```

```
Release() {  
  [ front := front + 1 ]  
}
```

var T
var front

```
Acquire() {  
  var ticket  
  [ havoc ticket; assume !T[ticket]; T[ticket] := true ] R  
  [ assume ticket == front ] N  
}
```

```
Release() {  
  [ front := front + 1 ]  
}
```

var back
var front

```
Acquire() {  
  var ticket  
  [ ticket := back; back := back + 1 ] N  
  [ assume ticket == front ] N  
}
```

```
Release() {  
  [ front := front + 1 ]  
}
```

Local reasoning is challenging

Read(*out* r): [assert lock == tid; r := x]
Write(v): [assert lock == tid; x := v]

$\text{lock} == \text{tid1} \wedge \text{lock} == \text{tid2} \models [r := x; x := v] \Rightarrow [x := v; r := x]$ ⚡

Commutativity of Read and Write requires information about two **tid** variables in different scopes being distinct from each other

Patterns of concurrency control

- Exclusive access
 - thread identifier, lock-protected access, memory ownership, ...
- Shared/exclusive access
 - barrier, read-shared memory access, vote collection, ...
- Need to encode variety of patterns
- ... without baking in each pattern

Our solution

1. Use **linear typing** and **logical reasoning** to establish global invariant
2. Exploit established invariant as a “**free assumption**” in verification conditions for commutativity and noninterference reasoning

Linear type system

1. Variables (global, local, parameters) have linearity annotations
2. Type system infers availability at every control location

<code>// x available</code>	<code>proc P (lin p)</code>	<code>proc P (lin_in p)</code>	<code>proc P (lin_out p)</code>
<code>// y unavailable</code>			
<code>y := x</code>	<code>// x available</code>	<code>// x available</code>	<code>// x unavailable</code>
<code>// x unavailable</code>	<code>call P(x)</code>	<code>call P(x)</code>	<code>call P(x)</code>
<code>// y available</code>	<code>// x available</code>	<code>// x unavailable</code>	<code>// x available</code>

3. $\Gamma: Value \rightarrow 2^{\mathbb{N}}$ e.g.: $\Gamma(tid) = \{tid\}$ $\Gamma(tidSet) = tidSet$

4. $Collect(c) = \left(\uplus_{x \in Lin \cap Glob} \Gamma(g(x)) \right) \uplus \left(\uplus_{(x,\ell) \in Available(c)} \Gamma(\ell(x)) \right)$

5. Invariant: $Collect(c)$ is a set

Exploiting the free assumption

Read(*linear tid*, out r): [assert lock == *tid*; r := x]
Write(*linear tid*, v): [assert lock == *tid*; x := v]

$\text{lock} == \text{tid1} \wedge \text{lock} == \text{tid2} \models [r := x; x := v] \Rightarrow [x := v; r := x]$ ⚡

$\text{IsSet}(\{\text{tid1}\} \uplus \{\text{tid2}\}) \wedge \text{lock} == \text{tid1} \wedge \text{lock} == \text{tid2} \models [r := x; x := v] \Rightarrow [x := v; r := x]$ ✓

↓ simplifies to

$\text{tid1} \neq \text{tid2}$

Atomic actions must preserve invariant

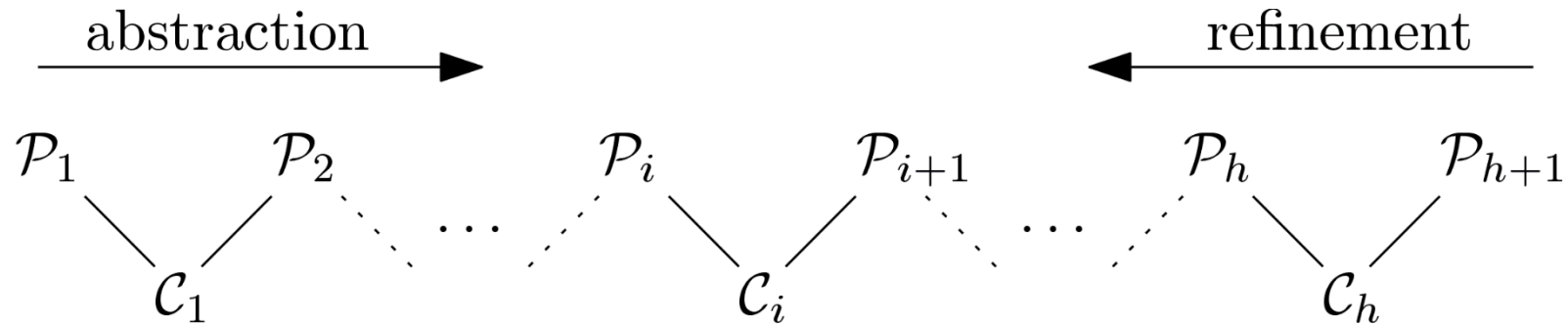
```
var lock : nat?  
var linear slots : set<nat>  
  
call Main()  
  
proc Main  
  while (*)  
    async Worker()  
  
proc Worker()  
  var linear tid : nat  
  call tid := ALLOC()  
  call ACQUIRE(tid)  
  // critical section  
  call RELEASE(tid)  
  
right ALLOC() : (linear tid: nat)  
  assume tid ∈ slots  
  slots := slots - tid  
  
right ACQUIRE(linear tid: nat)  
  assume lock == NIL  
  lock := tid  
  
left RELEASE(linear tid: nat)  
  assert lock == tid  
  lock := NIL
```

$$\Gamma(\text{slots}') \uplus \Gamma(\text{tid}') \subseteq \Gamma(\text{slots})$$

Patterns of concurrency control

- Exclusive access
 - thread identifier, lock-protected access, memory ownership, ...
- Shared/exclusive access
 - barrier, read-shared memory access, vote collection, ...
- Need to encode variety of patterns
- ... without baking in each pattern
- All patterns mentioned above are encodable by a suitable choice for Γ

A chain of concurrent programs



- $\mathcal{P}_1, \dots, \mathcal{P}_{h+1}$ are **concurrent programs**
 - \mathcal{P}_i refines \mathcal{P}_{i+1} for all $i \in [1, h]$
- $\mathcal{C}_1, \dots, \mathcal{C}_h$ are **concurrent checker programs**
 - safety of \mathcal{C}_i justifies \mathcal{C}_i refines \mathcal{C}_{i+1} for all $i \in [1, h]$
- Goal
 - Express $\mathcal{P}_1, \dots, \mathcal{P}_{h+1}$ and the key insight of $\mathcal{C}_1, \dots, \mathcal{C}_h$ in a single **layered concurrent program** \mathcal{LP}
 - Generate $\mathcal{C}_1, \dots, \mathcal{C}_h$ automatically from \mathcal{LP}

1 **var** b : bool

call Main()

proc Main
 while (*)
 async Worker()

proc Worker()

 call Alloc()
 call Enter()
 // critical section
 call Leave()

proc Alloc() : ()
 skip

proc Enter()
 var success : bool
 while (true)
 call success := CAS()
 if (success) break

proc Leave()
 call RESET()

atomic CAS() : (s: bool)
 if (b) s := false
 else s, b := true, true

atomic RESET()
 assert b
 b := false

2 **var** lock : nat?
var *linear* slots : set<nat>

call Main()

proc Main
 while (*)
 async Worker()

proc Worker()
 var *linear* tid : nat
 call tid := ALLOC()
 call ACQUIRE(tid)
 // critical section
 call RELEASE(tid)

right ALLOC() : (*linear* tid: nat)
 assume tid ∈ slots
 slots := slots - tid

right ACQUIRE(*linear* tid: nat)
 assume lock == NIL
 lock := tid

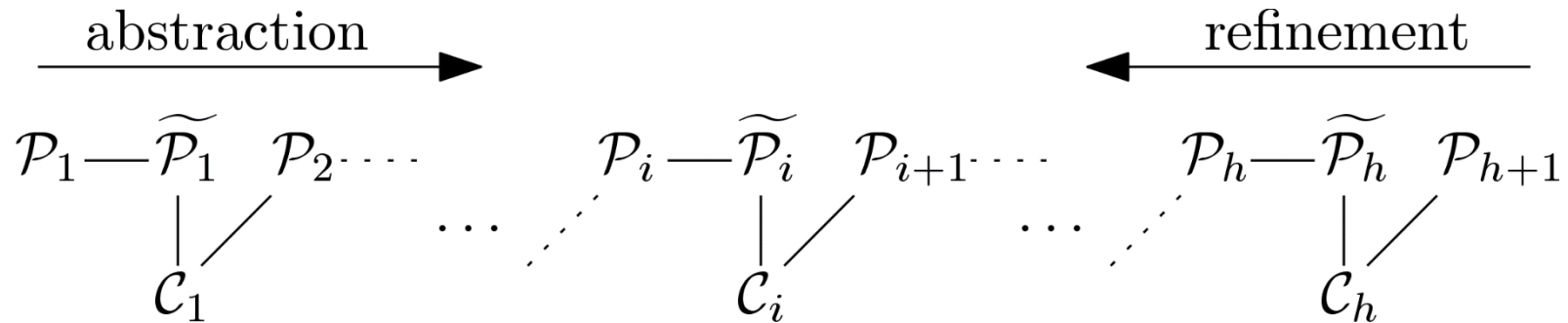
left RELEASE(*linear* tid: nat)
 assert lock == tid
 lock := NIL

3

call SKIP()

both SKIP()
 skip

A chain of concurrent programs



- $\mathcal{P}_1, \dots, \mathcal{P}_{h+1}$ are concurrent programs
 - \mathcal{P}_i refines \mathcal{P}_{i+1} for all $i \in [1, h]$
- $\mathcal{C}_1, \dots, \mathcal{C}_h$ are concurrent checker programs
 - safety of \mathcal{C}_i justifies \mathcal{P}_i refines \mathcal{P}_{i+1} for all $i \in [1, h]$
- \mathcal{C}_i is constructed in two steps
 - (optionally) add computation to \mathcal{P}_i to get $\tilde{\mathcal{P}}_i$
 - instrument $\tilde{\mathcal{P}}_i$ to obtain \mathcal{C}_i

```

var b : bool

proc Main
  while (*)
    async Worker()

proc Worker()

  call Alloc()
  call Enter()
  // critical section
  call Leave()

proc Alloc() : ()

proc Enter()
  var success : bool
  while (true)
    call success := CAS()
    if (success)

      break

proc Leave()
  call RESET()

atomic CAS() : (s: bool)
  if (b) s := false
  else s, b := true, true

atomic RESET()
  assert b
  b := false

```

```

var lock : nat?
var linear slots : set<nat>
var pos : nat

predicate InvAlloc
  slots = [pos, ∞)

iaction iIncr() : (linear tid : nat)
  assert InvAlloc
  tid := pos
  pos := pos + 1
  slots := slots - tid

iaction iSetLock(v: nat)
  lock := v

```

```

var b : bool

proc Main
  while (*)
    async Worker()

proc Worker()
  var linear tid: nat
  call tid := Alloc()
  call Enter(tid)
  // critical section
  call Leave(tid)

proc Alloc() : (linear tid: int)
  icall tid := iIncr()

proc Enter(linear tid: int)
  var success : bool
  while (true)
    call success := CAS()
    if (success)
      icall iSetLock(tid)
    break

proc Leave(linear tid: int)
  call RESET()
  icall iSetLock(nil)

atomic CAS() : (s: bool)
  if (b) s := false
  else s, b := true, true

atomic RESET()
  assert b
  b := false

```

Layered concurrent program

```
var b@[0,1] : bool
var lock@[1,2] : nat?
var linear slots@[1,2] : set<nat>
var pos@[1,1] : nat

call Main()

proc Main@2()
refines SKIP
  while (*)
    async call Worker()

left proc Worker@2()
refines SKIP
  var linear tid@1 : nat
  call tid := Alloc()
  call Enter(tid)
  call Leave(tid)
```

```
right ACQUIRE@[2,2](linear tid : nat)
  assume lock == 0
  lock := tid

left RELEASE@[2,2](linear tid : nat)
  assert lock == tid
  lock := 0

proc Enter@1(linear tid@1 : nat)
refines ACQUIRE
  var success@0 : bool
  while (true)
    call success := Cas()
    if (success)
      icall iSetLock(tid)
      break

proc Leave@1(linear tid@1 : nat)
refines RELEASE
  call Reset()
  icall iSetLock(nil)

iaction iSetLock@1(v : nat?)
  lock := v
```

```
right ALLOC@[2,2]() : (linear tid : nat)
  assume tid ∈ slots
  slots := slots - tid

proc Alloc@1() : (linear tid@1 : nat)
refines ALLOC
  icall tid := iIncr()

predicate InvAlloc
  slots = [pos, ∞)

iaction iIncr@1() : (linear tid : nat)
  assert InvAlloc
  tid := pos
  pos := pos + 1
  slots := slots - tid
```

```
atomic CAS@[1,1]() : (s: bool)
  if (b) s := false
  else s, b := true, true

atomic RESET@[1,1]()
  assert b
  b := false

proc Cas@0() : (success@0 : bool)
refines CAS

proc Reset@0()
refines RESET
```

Layered concurrent program

Layer 1

```
var b@[0,1] : bool
var lock@[1,2] : nat?
var linear slots@[1,2] : set<nat>
var pos@[1,1] : nat

call Main()

proc Main@2()
refines SKIP
  while (*)
    async call Worker()

left proc Worker@2()
refines SKIP
  var linear tid@1 : nat
  call tid := Alloc()
  call Enter(tid)
  call Leave(tid)
```

```
right ACQUIRE@[2,2](linear tid : nat)
  assume lock == 0
  lock := tid

left RELEASE@[2,2](linear tid : nat)
  assert lock == tid
  lock := 0

proc Enter@1(linear tid@1: nat)
refines ACQUIRE
  var success@0 : bool
  while (true)
    call success := CAS()
    if (success)
      icall iSetLock(tid)
      break

proc Leave@1(linear tid@1 : nat)
refines RELEASE
  call RESET()
  icall iSetLock(nil)

iaction iSetLock@1(v: nat?)
  lock := v
```

```
right ALLOC@[2,2]() : (linear tid : nat)
  assume tid ∈ slots
  slots := slots - tid

proc Alloc@1() : (linear tid@1 : nat)
refines ALLOC
  icall tid := iIncr()

predicate InvAlloc
  slots = [pos, ∞)

iaction iIncr@1() : (linear tid : nat)
  assert InvAlloc
  tid := pos
  pos := pos + 1
  slots := slots - tid
```

```
atomic CAS@[1,1]() : (s: bool)
  if (b) s := false
  else s, b := true, true

atomic RESET@[1,1]()
  assert b
  b := false

proc Cas@0() : (success@0 : bool)
refines CAS

proc Reset@0()
refines RESET
```

Layered concurrent program

Layer 2

```
var b@[0,1] : bool
var lock@[1,2] : nat?
var linear slots@[1,2] : set<nat>
var pos@[1,1] : nat

call Main()

proc Main@2()
refines SKIP
  while (*)
    async call Worker()

left proc Worker@2()
refines SKIP
  var linear tid@1 : nat
  call tid := ALLOC()
  call ACQUIRE(tid)
  call RELEASE(tid)
```

```
right ACQUIRE@[2,2](linear tid : nat)
  assume lock == 0
  lock := tid

left RELEASE@[2,2](linear tid : nat)
  assert lock == tid
  lock := 0

proc Enter@1(linear tid@1: nat)
refines ACQUIRE
  var success@0 : bool
  while (true)
    call success := Cas()
    if (success)
      icall iSetLock(tid)
      break

proc Leave@1(linear tid@1 : nat)
refines RELEASE
  call Reset()
  icall iSetLock(nil)

iaction iSetLock@1(v: nat?)
  lock := v
```

```
right ALLOC@[2,2]() : (linear tid : nat)
  assume tid ∈ slots
  slots := slots - tid

proc Alloc@1() : (linear tid@1 : nat)
refines ALLOC
  icall tid := iIncr()

predicate InvAlloc
  slots = [pos, ∞)

iaction iIncr@1() : (linear tid : nat)
  assert InvAlloc
  tid := pos
  pos := pos + 1
  slots := slots - tid
```

```
atomic CAS@[1,1]() : (s: bool)
  if (b) s := false
  else s, b := true, true

atomic RESET@[1,1]()
  assert b
  b := false

proc Cas@0() : (success@0 : bool)
refines CAS

proc Reset@0()
refines RESET
```

Layered concurrent program

Layer 3

```
var b@[0,1] : bool
var lock@[1,2] : nat?
var linear slots@[1,2] : set<nat>
var pos@[1,1] : nat

call SKIP()

proc Main@2()
refines SKIP
  while (*)
    async call Worker()

left proc Worker@2()
refines SKIP
  var linear tid@1 : nat
  call tid := Alloc()
  call Enter(tid)
  call Leave(tid)
```

```
right ACQUIRE@[2,2](linear tid : nat)
  assume lock == 0
  lock := tid

left RELEASE@[2,2](linear tid : nat)
  assert lock == tid
  lock := 0

proc Enter@1(linear tid@1 : nat)
refines ACQUIRE
  var success@0 : bool
  while (true)
    call success := Cas()
    if (success)
      icall iSetLock(tid)
      break

proc Leave@1(linear tid@1 : nat)
refines RELEASE
  call Reset()
  icall iSetLock(nil)

iaction iSetLock@1(v : nat?)
  lock := v
```

```
right ALLOC@[2,2]() : (linear tid : nat)
  assume tid ∈ slots
  slots := slots - tid

proc Alloc@1() : (linear tid@1 : nat)
refines ALLOC
  icall tid := iIncr()

predicate InvAlloc
  slots = [pos, ∞)

iaction iIncr@1() : (linear tid : nat)
  assert InvAlloc
  tid := pos
  pos := pos + 1
  slots := slots - tid
```

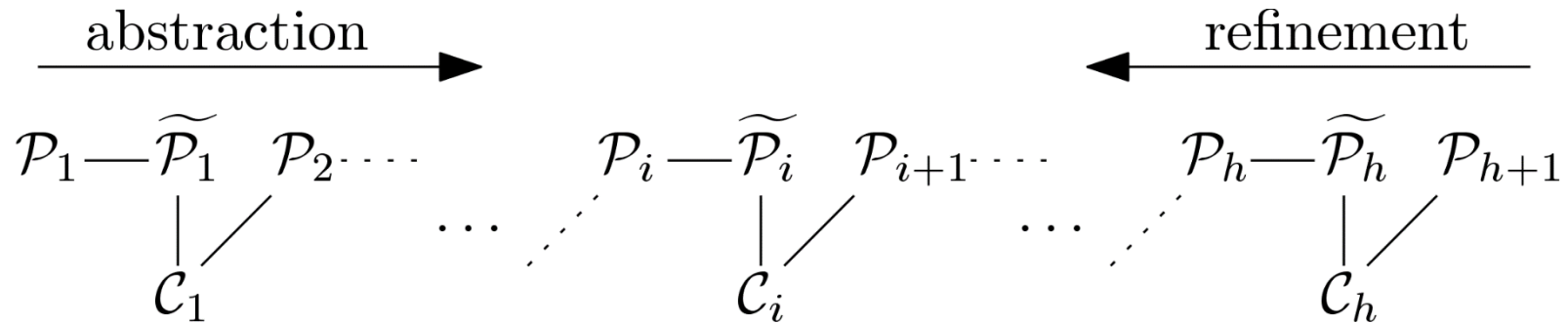
```
atomic CAS@[1,1]() : (s: bool)
  if (b) s := false
  else s, b := true, true

atomic RESET@[1,1]()
  assert b
  b := false

proc Cas@0() : (success@0 : bool)
refines CAS

proc Reset@0()
refines RESET
```

A chain of concurrent programs



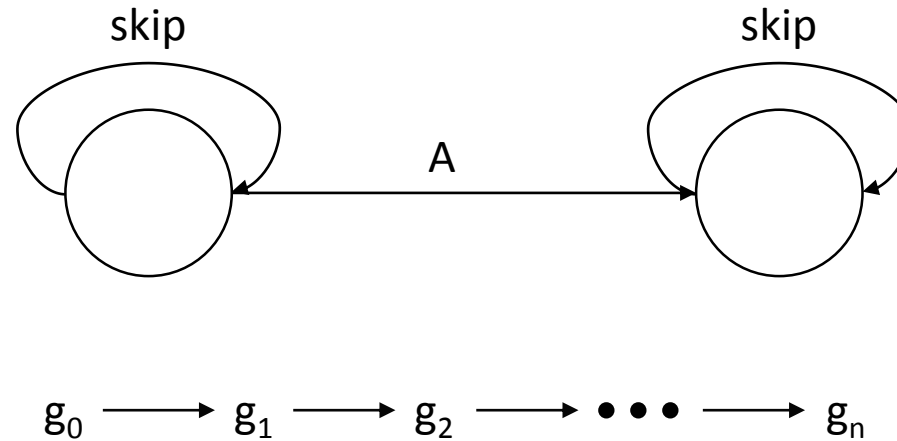
- $\mathcal{P}_1, \dots, \mathcal{P}_{h+1}$ are concurrent programs
 - \mathcal{P}_i refines \mathcal{P}_{i+1} for all $i \in [1, h]$
- $\mathcal{C}_1, \dots, \mathcal{C}_h$ are concurrent checker programs
 - safety of \mathcal{C}_i justifies \mathcal{P}_i refines \mathcal{P}_{i+1} for all $i \in [1, h]$
- \mathcal{C}_i is constructed in two steps
 - (optionally) add computation to \mathcal{P}_i to get $\tilde{\mathcal{P}}_i$
 - instrument $\tilde{\mathcal{P}}_i$ to obtain \mathcal{C}_i

Making interference explicit

```
proc Leave(linear tid)
refines RELEASE
  yield
  call RESET()
  icall iSetLock(nil)
  yield
```

```
proc Enter(linear tid)
refines ACQUIRE
  yield
  while (true)
    call success := CAS()
    if (success)
      icall iSetLock(tid)
      break;
  yield
  yield
```


Refinement checking



A and skip are disjoint

$pc_0 = \text{false}$
 $\text{assert } g_i \neq g_{i+1} \Rightarrow \neg pc_i \wedge A(g_i, g_{i+1})$
 $pc_{i+1} = pc_i \vee g_i \neq g_{i+1}$
 $\text{assert } pc_n$

In general

$pc_0 = \text{false}$
 $\text{assert } g_i \neq g_{i+1} \Rightarrow \neg pc_i \wedge A(g_i, g_{i+1})$
 $pc_{i+1} = pc_i \vee g_i \neq g_{i+1}$
 $\text{done}_0 = \text{false}$
 $\text{done}_{i+1} = \text{done}_i \vee A(g_i, g_{i+1})$
 $\text{assert } \text{done}_n$

```
macro *CHANGED* is !(lock == _lock && slots == _slots)
macro *RELEASE* is lock == nil && slots == _slots
macro *ACQUIRE* is _lock == nil && lock == tid && slots == _slots
```

```
proc Leave(linear tid)
  var _lock, _slots, pc, done
  pc, done := false, false
  yield
  _lock, _slots := lock, slots
  assume pc || lock == tid

  call RESET()
  icall iSetLock(nil)

  assert *CHANGED* ==> (!pc && *RELEASE*)
  pc := pc || *CHANGED*
  done := done || *RELEASE*
  yield
  assert done
```

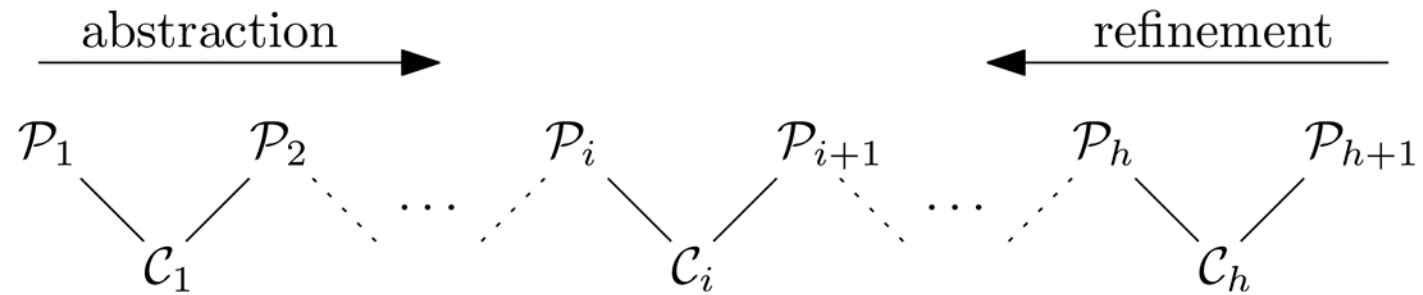
```
proc Enter(linear tid)
  var success, _lock, _slots, pc, done
  pc, done := false, false
  yield
  _lock, _slots := lock, slots
  assume pc || true

  while (true)
    call success := CAS()
    if (success)
      icall iSetLock(tid)
      break;

    assert *CHANGED* ==> (!pc && *ACQUIRE*)
    pc := pc || *CHANGED*
    done := done || *ACQUIRE*
    yield
    _lock, _slots := lock, slots
    assume pc || true

  assert *CHANGED* ==> (!pc && *ACQUIRE*)
  pc := pc || *CHANGED*
  done := done || *ACQUIRE*
  yield
  assert done
```

So far ...



- How do we verify concurrent checker programs $\mathcal{C}_1, \dots, \mathcal{C}_h$
 - Pick your favorite concurrent verifier
- CIVL implements the Owicki-Gries method in two steps
 - compile away interference using invariants attached to yield statements
 - leverage sequential verification-condition generation

Compiling interference away

yield I

```
assert I
check noninterference
havoc globals
assume I
update snapshot
```

call P

```
check noninterference
call P
update snapshot
```

async P

```
if *
  call P
  assume false
```

call P1 || P2

```
check noninterference
if *
  call P1
  assume false
elsif *
  call P2
  assume false
havoc call targets
havoc globals
assume post(P1)  $\wedge$  post(P2)
update snapshot
```

check noninterference

```
assert  $\forall$  locals.  $I_1(\text{locals}, \text{snapshot}) \Rightarrow I_1(\text{locals}, \text{globals})$ 
assert  $\forall$  locals.  $I_2(\text{locals}, \text{snapshot}) \Rightarrow I_2(\text{locals}, \text{globals})$ 
...
```

New verification problems introduced by CIVL

- CIVL expresses gated atomic actions as an atomic code block
- Does atomic block A refine atomic block B?
 - In checker program
 - In commutativity checking
- Is atomic block A nonblocking?
 - checking a left mover

Atomic block

GlobalVar = $\{g_1, \dots, g_m\}$
LocalVar = $\{l_1, \dots, l_n\}$

$S ::= x := e \mid \text{assume } e \mid \text{assert } e \mid S ; S \mid S \blacksquare S$

$\text{Good}(S) = \{ G \mid \neg \exists L. (G \cdot L, S) \Rightarrow^* \perp \}$
 $\text{Trans}(S) = \{ (G, G') \mid \exists L, L'. (G \cdot L, S) \Rightarrow^* (G' \cdot L', \varepsilon) \}$

S1 refines S2 iff

- $\text{Good}(S2) \subseteq \text{Good}(S1)$
- $\text{Good}(S2) \bullet \text{Trans}(S1) \subseteq \text{Trans}(S2)$

S is nonblocking iff

- $\text{Good}(S) \subseteq \exists G'. \text{Trans}(G, G')$

Calculating Good and Trans

$$\text{wp}(x := e, \varphi) = \varphi[x/e]$$

$$\text{wp}(\text{assume } e, \varphi) = e \Rightarrow \varphi$$

$$\text{wp}(\text{assert } e, \varphi) = e \wedge \varphi$$

$$\text{wp}(S1 ; S2, \varphi) = \text{wp}(S1, \text{wp}(S2, \varphi))$$

$$\text{wp}(S1 \blacksquare S2, \varphi) = \text{wp}(S1, \varphi) \wedge \text{wp}(S2, \varphi)$$

$$\text{tr}(x := e, \varphi) = \varphi[x/e]$$

$$\text{tr}(\text{assume } e, \varphi) = e \wedge \varphi$$

$$\text{tr}(\text{assert } e, \varphi) = e \wedge \varphi$$

$$\text{tr}(S1 ; S2, \varphi) = \text{tr}(S1, \text{tr}(S2, \varphi))$$

$$\text{tr}(S1 \blacksquare S2, \varphi) = \text{tr}(S1, \varphi) \vee \text{tr}(S2, \varphi)$$

$$\text{Good}(S) = \forall l_1, \dots, l_n. \text{wp}(S, \text{true})$$

$$\text{Trans}(S) = \exists l_1, \dots, l_n. \text{tr}(S, g_1 = g_1' \wedge \dots \wedge g_m = g_m')$$

S	Good(S)	Trans(S)
$\begin{array}{l} l := g + 1 \\ g := l \end{array}$	true	$g + 1 = g'$
$\begin{array}{l} \text{assume } g \leq l \\ g := l \end{array}$	true	$\exists l. g \leq l \wedge l = g'$
$\begin{array}{l} \text{assume } g \leq l \\ g := l \\ \text{assert } 0 \leq g \end{array}$	$\forall l. g \leq l \Rightarrow 0 \leq l$	$\exists l. g \leq l \wedge 0 \leq l \wedge l = g'$

Quantifiers are a problem

Is $\varphi \Rightarrow \psi$ valid?

- SMT solvers become unpredictable
- Universal quantifier in φ is a problem
- Existential quantifier in ψ is a problem

Heuristics for eliminating quantifiers

Eliminate x from $\exists x. \varphi(x, y)$:

- find $E(y)$ such that $\varphi(x, y) \Rightarrow x = E(y)$ is valid
- $\exists x. \varphi(x, y)$ is equivalent to $\varphi(E(y), y)$

Eliminate x from $\exists x. \varphi(x, y)$:

- split φ into $\varphi_1 \vee \varphi_2$
- find $E_1(y)$ and $E_2(y)$ such that $\varphi_1(x, y) \Rightarrow x = E_1(y)$ and $\varphi_2(x, y) \Rightarrow x = E_2(y)$
- $\exists x. \varphi(x, y)$ is equivalent to $\varphi_1(E_1(y), y) \vee \varphi_2(E_2(y), y)$

Look for equalities in path condition:

$x = e$

$e' = A[e := x] \rightarrow x = e'[e]$

...

Eliminate x from $\forall x. \varphi(x, y)$:

- find $E(y)$ such that $\varphi(x, y) \vee x = E(y)$ is valid
- $\forall x. \varphi(x, y)$ is equivalent to $\varphi(E(y), y)$

Eliminate x from $\forall x. \varphi(x, y)$:

- split φ into $\varphi_1 \wedge \varphi_2$
- find $E_1(y)$ and $E_2(y)$ such that $\varphi_1(x, y) \vee x = E_1(y)$ and $\varphi_2(x, y) \vee x = E_2(y)$
- $\forall x. \varphi(x, y)$ is equivalent to $\varphi_1(E_1(y), y) \wedge \varphi_2(E_2(y), y)$

CIVL in relation to ...

- Floyd-Hoare (rely-guarantee, concurrent separation logic, ...)
 - CIVL departs from the orthodoxy of pre/post-conditions
 - CIVL is less modular but more flexible
- Model checking (aka automatic verification of decidable abstractions)
 - CIVL addresses programmer-computer interaction
 - CIVL is less automated but more general
- Types and process algebra
 - CIVL is less automated but more expressive

Unsolved problems

- Concurrent programming language
 - Compiles to CIVL for verification
 - Generates executable code
- Modularity
 - Minimize cross-module interference checks
- Other (more automated) techniques for verifying checker programs
- Better PL and IDE support for understanding layers
- Better decision procedures

$$\frac{0 < N \quad A \subseteq [1, N] \quad B \subseteq [1, N] \quad B \subseteq A \quad |B| == N}{|A| == N}$$